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Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	1	10/706720	US-PGPUB; USPAT	OR	OFF	2006/04/28 10:52
S2	1	"6281878".pn.	US-PGPUB; USPAT	OR	OFF	2006/04/27 11:50
S3	2651	(hologram holographic) and keyboard	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/27 14:17
S4	30	(hologram holographic) near3 keyboard	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/27 14:34
S5	0	2000/246558	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/27 14:34
S6	2	"2000246558"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/27 14:34
S7	1445	virtual adj keyboard	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/27 14:34
S8	29	virtual adj keyboard and (hologram holograph holograph\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/27 14:35
S9	24961	image\$2 near10 compar\$4 and input and location	US-PGPUB; USPAT	OR	OFF	2006/04/27 15:41
S10	88	virtual adj keyboard and image\$2 near10 compar\$4	US-PGPUB; USPAT	OR	OFF	2006/04/27 15:41
S11	4	virtual adj keyboard and image\$2 near10 compar\$4 and (holo\$7)	US-PGPUB; USPAT	OR	OFF	2006/04/27 15:43
S12	27	virtual adj keyboard and image near10 difference	US-PGPUB; USPAT	OR	OFF	2006/04/27 15:48
S13	194	difference near5 pattern same image and analysis and location and input	US-PGPUB; USPAT	OR	OFF	2006/04/27 15:48

S14	11	difference near5 pattern same image and analysis and location and input and holog\$5	US-PGPUB; USPAT	OR	OFF	2006/04/27 15:50
S15	276	difference near5 (image pattern) and analysis and location and input and holog\$5	US-PGPUB; USPAT	OR	OFF	2006/04/27 15:50
S16	41	difference near5 (image pattern) and analysis and location and input and holog\$5 and keyboard	US-PGPUB; USPAT	OR	OFF	2006/04/27 15:51
S17	1624	345/168.ccls.	US-PGPUB; USPAT	OR	OFF	2006/04/27 15:53
S18	849	345/169.ccls.	US-PGPUB; USPAT	OR	OFF	2006/04/27 15:51
S19	4	345/169.ccls. and holog\$5	US-PGPUB; USPAT	OR	OFF	2006/04/27 15:51
S20	4	345/168.ccls. and holog\$4	US-PGPUB; USPAT	OR	OFF	2006/04/27 16:27
S21	10200	analyz\$4 same image same differe\$3	US-PGPUB; USPAT	OR	OFF	2006/04/27 16:27
S22	4155	analyz\$4 same image same differe\$3 and location same (find determin\$4 calculat\$4)	US-PGPUB; USPAT	OR	OFF	2006/04/27 16:28
S23	1064	analyz\$4 same image same differe\$3 and location same (find determin\$4 calculat\$4) and project	US-PGPUB; USPAT	OR	OFF	2006/04/27 16:28
S24	845	analyz\$4 same image same differe\$3 and location same (find determin\$4 calculat\$4) and project and camera	US-PGPUB; USPAT	OR	OFF	2006/04/27 16:29
S25	58	analyz\$4 same image same differe\$3 same location same (find determin\$4 calculat\$4) and project and camera	US-PGPUB; USPAT	OR	OFF	2006/04/27 16:29
S26	36	analyz\$4 same image same differe\$3 same location same (find determin\$4 calculat\$4) and project and camera and input	US-PGPUB; USPAT	OR	OFF	2006/04/27 16:29
S27	8	analyz\$4 same image same differe\$3 same location same (find determin\$4 calculat\$4) and project and camera and input and keyboard	US-PGPUB; USPAT	OR	OFF	2006/04/27 16:29
S28	81	analyz\$4 same image same differe\$3 same location same (find determin\$4 calculat\$4) and camera and input and keyboard	US-PGPUB; USPAT	OR	OFF	2006/04/27 16:30

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S29	9	analyz\$4 same image same differe\$3 same location same (find determin\$4 calculat\$4) and camera and input and keyboard and holog\$4	US-PGPUB; USPAT	OR	OFF	2006/04/27 16:31
S30	1092	virtual adj keyboard	US-PGPUB; USPAT	OR	OFF	2006/04/27 16:31
S31	53	virtual adj keyboard and image same differen\$4 same location	US-PGPUB; USPAT	OR	OFF	2006/04/27 16:31
S32	35	virtual adj keyboard and image same differen\$4 same location and camera	US-PGPUB; USPAT	OR	OFF	2006/04/27 16:44
S33	10	interactive near3 holog\$5	US-PGPUB; USPAT	OR	OFF	2006/04/27 16:44
S34	5246	image same reference same difference same (position location)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/28 10:52
S35	2268	image same reference same difference same (position location) and camera	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/28 10:53
S36	1516	image same reference same difference same (position location) and camera and input	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/28 10:53
S37	282	image same reference same difference same (position location) and camera and input and keyboard	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/28 10:53
S38	12	image same reference same difference same (position location) and camera and input and keyboard and holog\$5	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/28 11:02
S39	182	image same reference same difference same (position location) and camera and holog\$5	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/28 10:53
S40	161	image same reference same difference same (position location) and camera and holog\$5 and input	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/28 10:53

S41	0	image same substract same (position location) and holog\$5 and (camera sensor) and input	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/28 11:04
S42	6	image same substract same (position location)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/28 11:03
S43	404	image same subtract same (position location)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/28 11:03
S44	7	image same subtract same (position location) and holog\$5 and (camera sensor) and input	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/28 11:06
S45	173	image same subtract same (position location) and (camera sensor) and input	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/28 11:06
S46	53	image same subtract same (position location) and (camera sensor) and input and keyboard	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/28 11:10
S47	99	bamji.in.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/28 11:10
S48	79	canesta.as.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/28 11:11
S49	0	canesta.as. and holog\$5	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/28 11:11
S50	3	canesta.as. and image same subtract	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/28 11:12

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S51	12	image same subtract same reference and input and holog\$5	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/28 11:30
S52	77	input and camera and location same (remove subtract) near6 (reference template base background normal)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/28 13:38
S53	173	input and camera and (position location) same (remove subtract) near6 (reference template base background normal)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/28 13:38
S54	19	input and camera and (position location) same (remove subtract) near6 (reference template base background normal) and pointer	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/28 13:41
S55	355	345/175.ccls.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/28 13:41
S56	2	345/175.ccls. and (remove subtract) near10 (reference background template)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/28 13:45
S57	2225	camera and (remove subtract) near10 (reference background template)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/28 13:46
S58	1920	camera and (remove subtract) near10 (reference background template) and (position location)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/28 13:46
S59	537	camera and (remove subtract) near10 (reference background template) and (position location) near10 (calculate determine)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/28 13:46
S60	57	camera and (remove subtract) near10 (reference background template) and (position location) near10 (calculate determine) and finger	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/28 13:51

S61	27	camera and (remove subtract) near10 (reference background template) and (position location)	US-PGPUB; USPAT; EPO; JPO;	OR	OFF	2006/04/28 13:51
		near10 (calculate determine) and holog\$5	DERWENT; IBM TDB			

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